

DEPARTMENT OF MATHEMATICS

Student's Name \_\_\_\_\_ Course# \_\_\_\_\_ Prob.# \_\_\_\_\_ Date \_\_\_\_\_  
 Section Instructor \_\_\_\_\_ Sec.# \_\_\_\_\_

GRADING


HONOR PLEDGE: I pledge on my honor that I have not given or received any unauthorized assistance on this examination or assignment.  
 Please write the exact wording of the pledge, followed by your signature, in the space below:

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P.11 (1)  $\langle \cdot, \cdot \rangle$  is bilinear and symmetric. ✓

Let  $p(x) = a + bx + cx^2 \in \mathbb{P}^2$ , then

$$\langle p, p \rangle = p(-1)^2 + p(0)^2 + p(1)^2 \geq 0 \quad \text{and}$$

$$\langle p, p \rangle = 0 \Rightarrow p(-1) = p(0) = p(1) = 0$$

$$\Rightarrow \left. \begin{array}{l} a - b + c = 0 \\ a = 0 \\ a + b + c = 0 \end{array} \right\} \Rightarrow p = 0$$

$$(2) \quad p(x) = 1, \quad q(x) = x \quad \Rightarrow \langle p, q \rangle = -1 + 0 + 1 = 0$$

$$(3) \quad \langle r, p \rangle = 0 \Rightarrow r(-1) + r(0) + r(1) = 0$$

$$\Rightarrow 3c + 2 = 0$$

$$\langle r, q \rangle = 0 \Rightarrow \langle x^2, x \rangle + b \langle x, x \rangle + c \langle x, 1 \rangle = 0$$

$$2b = 0$$

$$\Rightarrow r(x) = x^2 - \frac{2}{3}$$

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Pb 2/

$$q(x_i) = y_i \Rightarrow \frac{1}{q(x_i)} = \frac{1}{y_i}$$

$$\Rightarrow a(3+x_i) + b \sin(x_i - \pi) = \frac{1}{y_i}$$

$$\begin{bmatrix} 3+1 & \sin(1-\pi) \\ 3+2 & \sin(2-\pi) \\ 3+3 & \sin(3-\pi) \\ 3+4 & \sin(4-\pi) \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} \frac{1}{10} \\ \frac{1}{15} \\ \frac{1}{14} \\ \frac{1}{23} \end{bmatrix}$$

$A$ 
 $x$ 
 $\bar{b}$

Normal eq.

$$A^T A x = A^T \bar{b}$$

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Pb 3/  
(1)

$p \in \text{span} \{t, t^2\}$        $f(t) = e^t \cos(t)$

$$\begin{cases} \langle p - f, w \rangle = 0 & \forall w \in \text{span} \{t, t^2\} \\ p = \alpha_1 t + \alpha_2 t^2 \end{cases}$$

$$\Rightarrow \underbrace{\begin{bmatrix} \langle t, t \rangle & \langle t^2, t \rangle \\ \langle t, t^2 \rangle & \langle t^2, t^2 \rangle \end{bmatrix}}_A \underbrace{\begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix}}_x = \underbrace{\begin{bmatrix} \langle e^t \cos(t), t \rangle \\ \langle e^t \cos(t), t^2 \rangle \end{bmatrix}}_b$$

(2) Matrix A is the Gram matrix of a lin indep. set  $\{t, t^2\} \Rightarrow A$  is SPD

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Pb 4 (1)  $A = BB^T$  is symmetric, moreover

$$x^T A x = x^T B B^T x = (B^T x)^T B^T x = \|B^T x\|^2 \geq 0 \quad \forall x \in \mathbb{R}^n$$

$$\text{if } x^T A x = 0 \Rightarrow \|B^T x\|^2 = 0$$

$$\Rightarrow x = \theta \text{ iff } B^T \text{ is non-singular}$$

(2)

$$A = \begin{pmatrix} 1 & 2 & 0 \\ 2 & 8 & 4 \\ 0 & 4 & 8 \end{pmatrix} \xrightarrow{R_2 - 2R_1} \begin{pmatrix} 1 & 2 & 0 \\ 0 & 4 & 4 \\ 0 & 4 & 8 \end{pmatrix} \xrightarrow{R_3 - R_2} \underbrace{\begin{pmatrix} 1 & 2 & 0 \\ 0 & 4 & 4 \\ 0 & 0 & 4 \end{pmatrix}}_U$$

$A$  symmetric and the pivots of  $U$  are  $> 0 \Rightarrow A$  is SPD.

Decomp  $A = LU \quad L = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} \quad D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{pmatrix}$

$$= LDL^T \quad D^{\frac{1}{2}} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$= (LD^{\frac{1}{2}})(LD^{\frac{1}{2}})^T = GG^T$$

$\hookrightarrow$  Cholesky decomp.

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Pb 5/ (1)  $S = \text{span} \{ a_1, a_2, a_3 \}$

$$a_1 = (0, -1, 1, 0)^T$$

$$a_2 = (2, 0, 2, 0)^T \quad a_3 = (-1, 0, 0, 1)^T$$

Gram-Schmidt:

$$v_1 = a_1$$

$$v_2 = a_2 - \frac{\langle a_2, v_1 \rangle}{\|v_1\|^2} v_1$$

$$v_3 = a_3 - \frac{\langle a_3, v_1 \rangle}{\|v_1\|^2} v_1 - \frac{\langle a_3, v_2 \rangle}{\|v_2\|^2} v_2$$

$$v_1 = a_1 = (0, -1, 1, 0)^T$$

$$v_2 = a_2 - 1 v_1 = (2, 1, 1, 0)^T$$

$$v_3 = a_3 - 0 v_1 + \frac{1}{3} v_2 = \left(-\frac{1}{3}, \frac{1}{3}, \frac{1}{3}, 1\right)^T$$

$$\Rightarrow S = \text{span} \{ v_1, v_2, v_3 \}$$

(2) Proj of  $b = (-1, 1, 1, 1)^T$  onto  $S = \text{span} \{ v_1, v_2, v_3 \}$

$$\text{Proj } b = w = \frac{\langle b, v_1 \rangle}{\|v_1\|^2} v_1 + \frac{\langle b, v_2 \rangle}{\|v_2\|^2} v_2 + \frac{\langle b, v_3 \rangle}{\|v_3\|^2} v_3$$

$$= 0 \cdot v_1 + 0 \cdot v_2 + \frac{2}{\frac{4}{3}} v_3$$

$$= \frac{3}{2} v_3$$